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On the products of bipolar harmonics

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Abstract The products of two and three bipolar harmonics $\mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32})$ are represented as the finite sums of powers of the three relative coordinates r_{32} , r_{31} and r_{21} . The complete (angular + radial) integrals of the products of the two and three bipolar harmonics in the basis of exponential radial functions are expressed as finite sums of the auxiliary three-particle integrals $\Gamma_{n,k,l}(\alpha, \beta, \gamma)$. The formulas derived in this study can be used to accelerate highly accurate computations of rotationally excited (bound) states in arbitrary three-body systems. In particular, we have constructed compact (400-term) variational wave functions for the triplet and singlet 2P(L = 1)-states in light two-electron atoms and ions. Highly accurate calculations (20–21 stable decimal digits in the total energy) of the triplet and singlet 2P(L = 1)-states in the two-electron Li⁺, Be²⁺, B³⁺ and C⁴⁺ ions are performed for the first time.

Keywords Few-body · Bipolar · Angular · Radial

The bipolar harmonics $\mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32})$ [1] are extensively used in various methods developed for highly accurate solutions of different three-body problems arising in atomic, molecular and nuclear physics. The functions, Eq. (2), are often used to represent the 'angular dependence' of two-electron wave functions. The effectiveness of bipolar harmonics as 'angular' functions follows from their explicit form which

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D. M. Wardlaw Department of Chemistry, Memorial University of Newfoundland, St. John's, NL A1C 5S7, Canada e-mail: dwardlaw@mun.ca reflects a number of transparent physical ideas. There are a number of successful generalizations of bipolar harmonics to four- and five-body systems, where the three- and four-polar harmonics arise. In this study, however, we restrict our analysis to threebody systems only. In general, the three-body bipolar harmonics are written in the form

$$\mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{x}, \mathbf{y}) = x_{31}^{\ell_1} y_{32}^{\ell_2} \sum_{m_1 m_2} C_{\ell_1 m_1 \ell_2 m_2}^{LM} Y_{\ell_1 m_1}(\mathbf{n}_x) Y_{\ell_2 m_2}(\mathbf{n}_y)$$
(1)

where $C_{\ell_1 m_1 \ell_2 m_2}^{LM}$ are the Clebsh-Gordan coefficients, while **x** and **y** are two fundamental vectors specifying the relative positions of the three particles. The vectors $\mathbf{n}_x = \frac{\mathbf{x}}{x}$ and $\mathbf{n}_y = \frac{\mathbf{y}}{y}$ are the unit-norm vectors used as arguments in the spherical harmonics. Let us designate three particles in our three-particle system by the numbers 1, 2 and 3. The 'natural' choice of the two fundamental vectors **x** and **y** in Eq. (1) for an arbitrary three-body system is $\mathbf{x} = \mathbf{r}_3 - \mathbf{r}_1 = \mathbf{r}_{31}$ and $\mathbf{y} = \mathbf{r}_3 - \mathbf{r}_2 = \mathbf{r}_{32}$. In this case each bipolar harmonic, Eq. (1), takes the form $\mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32})$ and contains the vectors \mathbf{r}_{31} and \mathbf{r}_{32} . Here and everywhere below in this study we assume that these two vectors are truly independent, i.e. $\mathbf{r}_{31} \neq \lambda \mathbf{r}_{32}$, where λ is a numerical constant. Finally, the explicit form of the bipolar harmonics takes the form

$$\mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32}) = r_{31}^{\ell_1} r_{32}^{\ell_2} \sum_{m_1 m_2} C_{\ell_1 m_1 \ell_2 m_2}^{LM} Y_{\ell_1 m_1}(\mathbf{n}_{31}) Y_{\ell_2 m_2}(\mathbf{n}_{32})$$
$$= r_{31}^{\ell_1} r_{32}^{\ell_2} \mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{n}_{31}, \mathbf{n}_{32})$$
(2)

Variational wave functions which include bipolar harmonics are used to approximate the actual wave functions of bound states with non-zero angular momentum L. In many papers the bipolar harmonics are called and considered as the 'angular parts' of basis functions. It is assumed that the additional 'radial' part of the total wave function depends upon the three radial coordinates r_{32} , r_{31} and r_{21} only, i.e., it does not contain any of the angular variables. It is clear that the bipolar harmonics with the same L and M values (or indexes) form the (2L + 1)-dimensional representation of the rotation group SO(3). The explicit form of the matrices which describe transformations of the bipolar harmonics during rotations can be found with the use of Eq. (2) and formulas from [2] and [3]. It can be shown that each matrix element is the product of two Clebsh–Gordan coefficients and two Wigner's D-functions. The explicit expression for these matrix elements can be reduced to another 'short' form, but below we will not need these formulas.

In this communication we develop the new method to operate with the bipolar harmonics. Our main interest below is related to the products of the two and three bipolar harmonics and angular integrals of such products. First, note that bipolar harmonics with the same LM indexes form the closed algebra, i.e. the product of two bipolar harmonics $\mathcal{Y}_{L_aM_a}^{\ell_1\ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32})$ and $\mathcal{Y}_{L_bM_b}^{\ell_3\ell_4}(\mathbf{r}_{31}, \mathbf{r}_{32})$ is always represented as the finite sum of bipolar harmonics with the different values of L_c and M_c . This can be written in the following form

$$\mathcal{Y}_{L_{a}M_{a}}^{\ell_{1}\ell_{2}}(\mathbf{r}_{31},\mathbf{r}_{32})\mathcal{Y}_{L_{b}M_{b}}^{\ell_{3}\ell_{4}}(\mathbf{r}_{31},\mathbf{r}_{32}) = \sum_{\ell_{a}\ell_{b}} f_{LM}(\ell_{1},\ell_{2},\ell_{3},\ell_{4},\ell_{5},\ell_{6};L_{a},M_{a},L_{b},M_{b},L_{c},M_{c})\mathcal{Y}_{L_{c}M_{c}}^{\ell_{5}\ell_{6}}(\mathbf{r}_{31},\mathbf{r}_{32})$$
(3)

where $f_{LM}(\ell_1, \ell_2, \ell_3, \ell_4; \ell_a, \ell_b)$ are the numerical coefficients which can be determined, e.g., by mulitplying the both sides of Eq. (3) by the different bipolar harmonics and performing integration of the both parts of arising equation over all angular variables.

Let us briefly discuss the integration over the angular variables in an arbitrary non-relativistic system of three particles. In general, to describe the non-relativistic quantum system of spinless particles one needs 9 (3×3) dynamical variables. Three of these nine variables describe the translations of the solid triangle of particles. The internal state of three-body system does not change during such translations. In actual cases these three (Galilean) translations can be separated by using an appropriate choice of internal coordinates. Formally, we can assume that after such a separation of translations one of the three particles, e.g. the third particle, will always be at rest. The remaining six coordinates are separated into two groups: (a) three coordinates which are rotationally invariant, i.e. they do not change during any rotation of the whole three-body system. The scalar coordinates which do not change during any rotation and/or translation of the three-body system can be chosen as the three interparticle distances r_{32} , r_{31} , r_{21} .

The choice of the three truly independent 'rotational' coordinates in the three-body system is slightly more complicated, since such coordinates must be related with the angular coordinates of the two vectors \mathbf{r}_{31} and \mathbf{r}_{32} . Let θ_1 , ϕ_1 and θ_2 , ϕ_2 be the spherical coordinates of these two vectors. In these coordinates for an elementary volume dV we can write

$$dV = r_{31}^2 dr_{31} sin\theta_{31} d\theta_{31} d\phi_{31} r_{32}^2 dr_{32} sin\theta_{32} d\theta_{32} d\phi_{32}$$
(4)

These six coordinates $(r_{31}, \theta_{31}, \phi_{31}, r_{32}, \theta_{32}, \phi_{32})$ can be used to describe an arbitrary three-body system. However, as it was shown by Hylleraas in [4] it is better to choose three-body coordinates in a different way. In [4] three radial variables were chosen as scalar interparticle distances (or interparticle coordinates) $r_{ij} = |\mathbf{r}_i - \mathbf{r}_j| = r_{ji}$, where (ij) = (32), (31), (21). On the other hand, it is clear that three angular variables can be chosen as the three Euler's angles $\phi_{31}, \theta_{31}, \phi_{32}$. In reality, one finds a number of advantages in calculations, if such a 'natural' choice of angular variables is used. In particular, in all earlier papers (see, e.g., [5–8] and references therein) three radial r_{32}, r_{31}, r_{21} and three angular variables $\phi_{31}, \theta_{31}, \phi_{32}$ were chosen as described here. In these variables an elementary volume dV takes the form

$$dV = r_{32}r_{31}r_{21}dr_{32}dr_{31}dr_{21}sin\theta_{31}d\theta_{31}d\phi_{32}d\phi_{31}$$
(5)

This part of our study can be concluded with the two following comments. First, the three radial r_{32} , r_{31} , r_{21} and three angular variables ϕ_{31} , θ_{31} , ϕ_{32} are semi-separated

from each other. This means that the angular integral of any function of these six variables integrated over three angular variables (or over Euler's angles) is a function of the three radial variables only. Furthermore, in many actual cases these functions of radial variables are written in a relatively simple, finite-term form. Second, the three radial variables r_{32} , r_{31} , r_{21} are not independent of each other, since e.g., $r_{21} \le r_{32}+r_{31}$ and $r_{31} \ge |r_{32} - r_{21}|$. Such constraints substantially complicate analytical and numerical calculations of three-body integrals. Therefore, in actual cases it is better to use three truly independent perimetric coordinates u_1 , u_2 , u_3 [9], which are related with the relative coordinates by the following linear transformation

$$u_1 = \frac{1}{2}(r_{31} + r_{21} - r_{21})$$
, $u_2 = \frac{1}{2}(r_{32} + r_{21} - r_{31})$, $u_3 = \frac{1}{2}(r_{32} + r_{31} - r_{21})$

The inverse relation takes the form

$$r_{32} = u_2 + u_3$$
, $r_{31} = u_1 + u_3$, $r_{32} = u_1 + u_2$

The Jacobian of the $(r_{32}, r_{31}, r_{21}) \rightarrow (u_1, u_2, u_3)$ transformation equals 2. The three perimetric coordinates u_1, u_2, u_3 are independent of each other and each of them varies between 0 and $+\infty$.

The formula for the angular integral of the product of the two bipolar harmonics can be written in the form

$$\oint d\Omega \mathcal{Y}_{LM}^{\ell_1 \ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32}) \mathcal{Y}_{LM}^{\ell_3 \ell_4}(\mathbf{r}_{31}, \mathbf{r}_{32}) = F_{\ell_1 \ell_2; \ell_3 \ell_4}^L(r_{32}, r_{31}, r_{21})$$
(6)

The explicit form of the radial $F_{\ell_1\ell_2;\ell_3\ell_4}^L$ function can be found with the use of Eq. (2) [5,7]. The result is

$$F_{\ell_{1}\ell_{2};\ell_{3}\ell_{4}}^{L}(r_{32},r_{31},r_{21}) = \frac{1}{2}(-1)^{L}r_{31}^{\ell_{1}+\ell_{3}}r_{32}^{\ell_{2}+\ell_{4}}\sqrt{[\ell_{1}][\ell_{2}][\ell_{3}][\ell_{4}]}\sum_{\lambda}(-1)^{\lambda}[\lambda] \begin{pmatrix} \ell_{1} \ \ell_{3} \ \lambda \\ 0 \ 0 \ 0 \end{pmatrix} \times \begin{pmatrix} \ell_{2} \ \ell_{4} \ \lambda \\ \ell_{2} \ \ell_{1} \ \lambda \end{pmatrix} P_{\lambda}(x)$$

$$(7)$$

where [a] = 2a + 1 and the notation $P_{\lambda}(x)$ stands for the Legendre polynomial of the order λ , where λ is a positive integer. Also, in this formula (and in some formulas below) we use the standard notations for the 3j- and 6j-symbols [10]. The sum over λ in Eq. (7) is always finite, since the product of two 3j-symbols is not zero only for those λ which are bounded between the following values: $max\{|\ell_1 - \ell_3|, |\ell_2 - \ell_4|\} \le \lambda \le min\{\ell_1 + \ell_3, \ell_2 + \ell_4\}$. Moreover, the product of these two 3j-symbols equals zero unless the two sums of the corresponding momenta $(\ell_1 + \ell_3 + \lambda \text{ and } \ell_2 + \ell_4 + \lambda)$ are even numbers. The variable x, in Eq. (7), is the following dimensionless ratio

$$x = \frac{r_{31}^2 + r_{32}^2 - r_{21}^2}{2r_{31}r_{32}} \tag{8}$$

This expression can be transformed with the use of the formula (8.911) from [11] for the Legendre polynomial $P_{\lambda}(x)$

$$P_{\lambda}(x) = \frac{1}{2^{\lambda}} \sum_{k=0}^{\Lambda} \frac{(-1)^{k} (2\lambda - 2k)!}{k! (\lambda - k)! (\lambda - 2k)!} x^{\lambda - 2k} = \frac{1}{2^{\lambda}} \sum_{k=0}^{\Lambda} a_{\lambda,k} x^{\lambda - 2k}$$
(9)

where $\Lambda = \left[\frac{\lambda}{2}\right]$ is the integer part of $\frac{\lambda}{2}$ and coefficients $a_{\lambda,k}$ are

$$a_{\lambda,k} = \frac{(-1)^k (2\lambda - 2k)!}{k! (\lambda - k)! (\lambda - 2k)!}$$

Now, by using the formula, Eq. (8), one finds the following expression for the $x^{\lambda-2k}$ factor from Eq. (9)

$$x^{\lambda-2k} = r_{31}^{2k-\lambda} r_{32}^{2k-\lambda} \sum_{n=0}^{\lambda-2k} C_{\lambda-2k}^{n} (r_{32}^2 - r_{21}^2)^n r_{32}^{2\lambda-4k-2n}$$
$$= \sum_{n=0}^{\lambda-2k} C_{\lambda-2k}^{n} \sum_{m=0}^{n} (-1)^m C_n^m r_{32}^{\lambda-2k-2n} r_{31}^{2k-\lambda+2n-2m} r_{21}^{2m}$$
(10)

where $k \leq \Lambda$ (see Eq. (9)) and notation C_b^a stands for the binomial coefficients (the number of combinations from *b* by *a*, where *a* and *b* are positive integer numbers).

The formula, Eq. (10), allows one to re-write the expression, Eq. (9) in the form

$$P_{\lambda}(x) = \frac{1}{2^{\lambda}} \sum_{k=0}^{\Lambda} a_{\lambda,k} \sum_{n=0}^{\lambda-2k} C_{\lambda-2k}^{n} \sum_{m=0}^{n} (-1)^{m} C_{n}^{m} r_{32}^{\lambda-2k-2n} r_{31}^{2k-\lambda+2n-2m} r_{21}^{2m}$$
(11)

Now, by using the formulas, Eqs. (10) and (11), we can derive the following finite-sum expression for the exponential integral of the Legendre polynomial $P_{\lambda}(x)$

$$I_{\ell_{2}+\ell_{4};\ell_{1}+\ell_{3}}(\alpha,\beta,\gamma;P_{\lambda}) = \int \int \int P_{\lambda}(x) \exp(-\alpha r_{32} - \beta r_{31} - \gamma r_{21}) r_{32}^{\ell_{2}+\ell_{4}+1} r_{31}^{\ell_{1}+\ell_{3}+1} r_{21} dr_{32} dr_{31} dr_{21}$$

$$= \frac{1}{2^{\lambda}} \sum_{k=0}^{\Lambda} a_{\lambda,k} \sum_{n=0}^{\lambda-2k} C_{\lambda-2k}^{n}$$

$$\times \sum_{m=0}^{n} (-1)^{m} C_{n}^{m} \Gamma_{\ell_{2}+\ell_{4}+\lambda-2k-2n+1,\ell_{1}+\ell_{3}+2k-\lambda+2n-2m+1,2m+1}(\alpha,\beta,\gamma) \quad (12)$$

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where $\Gamma_{k,l,n}(a, b, c)$ is the basic three-body integral defined in [12]. The definition of the basic three-body integral is written in the form

$$\Gamma_{k;l;n}(\alpha,\beta,\gamma) = \int \int \int r_{32}^{k} r_{31}^{l} r_{21}^{n} \exp(-\alpha r_{32} - \beta r_{31} - \gamma r_{21}) dr_{32} dr_{31} dr_{21}$$
(13)

where all indexes k, l, n are assumed to be non-negative integer numbers. The analytical formula used for numerical computations of such integrals is obtained from Eq. (13) by performing integration in perimetric coordinates [8]

$$\Gamma_{k;l;n}(\alpha,\beta,\gamma) = 2 \sum_{k_1=0}^{k} \sum_{l_1=0}^{l} \sum_{n_1=0}^{n} C_{k_1}^{k} C_{l_1}^{l} C_{n_1}^{n} \frac{(l-l_1+k_1)!}{(\alpha+\beta)^{l-l_1+k_1+1}} \frac{(k-k_1+n_1)!}{(\alpha+\gamma)^{k-k_1+n_1+1}} \frac{(n-n_1+l_1)!}{(\beta+\gamma)^{n-n_1+l_1+1}}$$

$$= 2 \cdot k! \cdot l! \cdot n! \sum_{k_1=0}^{k} \sum_{l_1=0}^{l} \sum_{n_1=0}^{n} \frac{C_{k_1}^{k_1}}{(\alpha+\beta)^{l-l_1+k_1+1}} \frac{(k-k_1+n_1)!}{(\alpha+\gamma)^{k-k_1+n_1+1}} \frac{(n-n_1+l_1)!}{(\beta+\gamma)^{n-n_1+l_1+1}}$$

$$(14)$$

where C_M^m are the binomial coefficients. The formula, Eq. (14), can also be written in a few other equivalent forms. The function $\frac{n!}{X^{n+1}}$ in Eq. (14) is the $A_n(X)$ function introduced by Larson [13]. The formula, Eq. (14), was produced forthe first time by one of the author (AMF) in the middle of 1980s (see, e.g., [8] and references therein). The formula, Eq. (14), has been used in calculations of various three-body integrals, e.g., integrals containing one or two Bessel functions [12].

With the use of the formulas derived above one can obtain the closed (i.e. finite term) analytical formula for the following exponential integral

$$\mathcal{F}_{\ell_{1}\ell_{2};\ell_{3}\ell_{4}}^{L}(a,b,c) = \int \int \int F_{\ell_{1}\ell_{2};\ell_{3}\ell_{4}}^{L}(r_{32},r_{31},r_{21}) \exp(-ar_{32}-br_{31}-cr_{21})r_{32}r_{31}r_{21}dr_{32}dr_{31}dr_{21} dr_{31}dr_{21} = \frac{1}{2}(-1)^{L}\sqrt{[\ell_{1}][\ell_{2}][\ell_{3}][\ell_{4}]} \sum_{\lambda} (-1)^{\lambda} \frac{[\lambda]}{2^{\lambda}} \begin{pmatrix} \ell_{1} \ \ell_{3} \ \lambda \\ 0 \ 0 \ 0 \end{pmatrix} \begin{pmatrix} \ell_{2} \ \ell_{4} \ \lambda \\ \ell_{2} \ \ell_{1} \ \lambda \end{pmatrix} \times \sum_{k=0}^{\Lambda} a_{\lambda,k} \sum_{n=0}^{\lambda-2k} C_{\lambda-2k}^{n} \times \sum_{m=0}^{n} (-1)^{m} C_{n}^{m} \Gamma_{\ell_{2}+\ell_{4}+\lambda-2k-2n+1,\ell_{1}+\ell_{3}+2k-\lambda+2n-2m+1,2m+1}(a,b,c)$$
(15)

The derivation of this formula was the main goal of our study. This formula is of great interest for numerical calculations of matrix elements which are needed to determine the total energies of bound states in three-body systems with $L \ge 1$ and calculate various expectation values. Recently, we have developed a number of fast numerical approaches to calculate the auxiliary three-particle integrals $\Gamma_{n,k,l}(a, b, c)$. This

allows one to accelerate substantially all numerical calculations of matrix elements (see below).

Note that the matrix elements of the potential energy are written in the form of Eq. (14) only in those cases when all interparticle interaction potentials are the scalar functions of interparticle distances r_{32} , r_{31} and r_{21} . Such cases include Coulomb threebody systems and three-body systems in which the potential energy is written in the form $V_a(r_{32}) + V_b(r_{31}) + V_c(r_{21})$. In more complex cases the interaction potential between each pair of particles can also be a function of angular coordinates. Analytical formulas for the matrix elements in such cases must include angular integrals of the products of three bipolar harmonics. Such integrals are discussed below.

Now, let us present the results of numerical calculations with the use of formulas derived above. These results are shown in Tables 1 and 2. In Table 1 we demonstrate the results of numerical calculations of the $I_{\ell_2+\ell_4;\ell_1+\ell_3}(\alpha, \beta, \gamma; P_{\lambda})$ and $\mathcal{F}_{\ell_1\ell_2;\ell_3\ell_4}^L(a, b, c)$ integrals, Eq. (15), determined for different numerical values of its arguments (a, b, c) and parameters $(L, (\ell_1, \ell_2), (\ell_3, \ell_4))$. The method of numerical computations of these (exponential) integrals is based on the formula, Eq. (15). However, for actual calculations this formula has been modified to avoid numerical instabilities which arise during summation of large numbers of positive and negative terms. The first formula, Eq. (12), was re-written in the form

$$I_{\ell_{2}+\ell_{4};\ell_{1}+\ell_{3}}(\alpha,\beta,\gamma;P_{\lambda}) = \frac{1}{2^{\lambda}} \sum_{k=0}^{\Lambda} |a_{\lambda,k}| \sum_{n=0}^{\lambda-2k} C_{\lambda-2k}^{n} \times \sum_{m=0}^{n} (-1)^{k+m} C_{n}^{m} \Gamma_{\ell_{2}+\ell_{4}+\lambda-2k-2n+1,\ell_{1}+\ell_{3}+2k-\lambda+2n-2m+1,2m+1}(\alpha,\beta,\gamma)$$
(16)

where $\Lambda = \left[\frac{\lambda}{2}\right]$, while the coefficients $|a_{\lambda,k}|$ are

$$|a_{\lambda,k}| = \frac{(2\lambda - 2k)!}{k!(\lambda - k)!(\lambda - 2k)!}$$

ℓ_1	ℓ_2	ℓ_3	ℓ_4	λ	$I_{\ell_1\ell_2;\ell_3\ell_4}(a,b,c;P_\lambda)$	L	$\mathcal{F}^L_{\ell_1\ell_2;\ell_3\ell_4}(a,b,c)$
1	0	1	0	1	0.20963264469930568E+00	1	0.13008789710134043E+00
1	1	1	1	1	0.11032101479039074E+01	2	0.72370337608449528E+00
1	1	2	0	1	0.11491009319449536E+01	2	0.69783486804905589E+00
1	2	2	1	2	0.33053241063178740E+02	3	0.83514739108659169E+01
1	2	1	2	2	0.34640478424614411E+02	3	0.69505739570548458E+01
3	0	1	2	2	0.18295480775566101E+02	3	0.14561365717576028E+02
3	0	0	3	3	0.58890134034481354E+02	3	0.29445067017240677E+02

Table 1 Numerical values of the $I_{\ell_2+\ell_4;\ell_1+\ell_3}(a, b, c; P_{\lambda})$ and $\mathcal{F}^L_{\ell_1\ell_2;\ell_3\ell_4}(a, b, c)$ integrals computed for different values of the $\ell_1, \ell_2, \ell_3, \ell_4, \lambda$ and L parameters

a = 1.55, b = 1.33 and c = 1.07 in all cases

	$E(^{1}P(L=1)\text{-state})$	$E({}^{3}P(L=1)\text{-state})$
∞ _{He}	-2.12384308649749	-2.13316419077725
⁴ He	-2.12354565412918	-2.13288064210349
³ He	-2.12344834501190	-2.13278787470796
∞_{Li}^+	-4.99335107777845	-5.02771568139695
∞ Be ²⁺	-9.11077162291325	-9.17497314304428
∞B^{3+}	-14.4772832652859	-14.5731376921778
$^{\infty}C^{4+}$	-21.0933323133828	-21.2217106964635

Table 2 The total energies *E* of the bound ${}^{1}P(L = 1)$ - and ${}^{3}P(L = 1)$ -states of some two-electron atoms and ions (in atomic units)

The total number of basis functions used to construct these short-term wave functions is 400

The sums of the positive and negative terms in Eq. (16) must be calculated separately. At the second step we have used the following formula

$$\mathcal{F}_{\ell_{1}\ell_{2};\ell_{3}\ell_{4}}^{L}(a,b,c) = \frac{1}{2}(-1)^{L}\sqrt{[\ell_{1}][\ell_{2}][\ell_{3}][\ell_{4}]}\sum_{\lambda}(-1)^{\lambda}[\lambda] \begin{pmatrix} \ell_{1} \ \ell_{3} \ \lambda \\ 0 \ 0 \ 0 \end{pmatrix} \begin{pmatrix} \ell_{2} \ \ell_{4} \ \lambda \\ 0 \ 0 \ 0 \end{pmatrix} \times \begin{cases} \ell_{3} \ \ell_{4} \ L \\ \ell_{2} \ \ell_{1} \ \lambda \end{cases} \cdot I_{\ell_{2}+\ell_{4};\ell_{1}+\ell_{3}}(\alpha,\beta,\gamma;P_{\lambda})$$
(17)

These two formulas are used for very fast and accurate calculations of the exponential integrals $\mathcal{F}_{\ell_1\ell_2;\ell_3\ell_4}^L(a, b, c)$ which can be found in each matrix element of the Hamiltonian and overlap matrices for the bound states with $L \ge 1$. By performing extensive numerical computations we have found that the method based on the modified formulas, Eqs. (16, 17), is fast, numerically reliable and can be applied in computations of different rotationally excited states, including highly excited states with $L \ge 15-20$.

In Table 2 we determine the total energies of the bound P(L = 1)-states of a number of three-body systems. These systems include the two-electron ${}^{\infty}$ He, ⁴He and ³He atoms and two-electron He-like ions: Li⁺, Be²⁺, B³⁺ and C⁴⁺. For the bound P(L = 1)-states we can perform highly accurate numerical calculations by using our old approach [8] and the new method described in this study. Therefore, we can compare the final accuracy of both methods and computational times needed to compute the same values. The nuclear masses of the ³He and ⁴He nuclei are 5495.8852 and 7294.2996 m_e , respectively [14]. The masses of the nuclei in all two-electron ions and the He atom are assumed to be infinite. For each of these systems we determine the total energies E (in atomic units) of the singlet 2¹P-states and triplet 2³P-states (see Table 2). Our trial wave functions contain N = 400 exponential basis functions. The explicit form of such wave functions is

$$\psi(r_{32}, r_{31}, r_{21}) = \frac{1}{\sqrt{2}} [1 + (-1)^{\epsilon} \hat{P}_{12}] \cdot \mathcal{Y}_{10}^{\ell_1 \ell_2}(\mathbf{r}_{31}, \mathbf{r}_{32}) \sum_{i=1}^{N} C_i exp(-\alpha_i r_{32} - \beta_i r_{31} - \gamma_i r_{21})$$
(18)

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Ion	Ν	$E(^{1}P(L=1)\text{-state})$	$E({}^{3}P(L=1)\text{-state})$
Li ⁺	2,500	-4.99335107778001736235	-5.027715681397367762165
Li ⁺	2,700	-4.99335107778001736242	-5.027715681397367762174
Li ⁺	2,850	-4.99335107778001736245	-5.027715681397367762180
Be ²⁺	2,500	-9.110771662291644408257	-9.174973143070973000582
Be ²⁺	2,700	-9.110771662291644408262	-9.174973143070973000594
Be ²⁺	2,850	-9.110771662291644408265	-9.174973143070973000601
B ³⁺	2,500	-14.47728326530779928311	-14.57313769221348004811
B ³⁺	2,700	-14.47728326530779928988	-14.57313769221348004813
B ³⁺	2,850	-14.47728326530779929427	-14.57313769221348004814
C ⁴⁺	2,500	-21.09333231338840905480	-21.22171069648805107794
C ⁴⁺	2,700	-21.09333231338840905491	-21.22171069648805107766
C ⁴⁺	2,850	-21.09333231338840905510	-21.22171069648805107771

Table 3 Highly accurate total energies E of the bound ${}^{1}P(L = 1)$ - and ${}^{3}P(L = 1)$ -states of some two-electron ions (in atomic units)

The total number of basis function is designated by N

where C_i are the linear variational coefficients, $\epsilon = 1$ in the case of the triplet states and $\epsilon = 2$ (or 0) in the case of the singlet states. The operator \hat{P}_{12} is the permutation of the two identical particles (electrons 1 and 2) and N is the total number of terms in the trial function. Analogous wave functions with N = 700 basis functions will later be used as short-term cluster functions in our highly accurate computations of the bound 2^1P - and 2^3P -states in these atomic systems. All such calculations are usually performed with the use of our two-stage optimization strategy [15].

Preliminary results of highly accurate computations of the bound 2^1P - and 2^3P -states in the Li⁺, Be²⁺, B³⁺ and C⁴⁺ ions are shown in Table 3. In these calculations we have used the short-term cluster wave functions with N = 400 terms from Table 2. The total number of basis functions used in our highly accurate computations was varied between 2,500 and 2,850 exponential functions. More accurate calculations of these states are possible at this moment, but they require larger computational resources than currently available to the authors. The total energies and other bound state properties of the bound 2^1P - and 2^3P -states in the Li⁺, Be²⁺, B³⁺ and C⁴⁺ ions have never been determined to high accuracy (these bound states play important roles in some applications). The results from Table 3 are preliminary, but they will be used to accelerate the following highly accurate computations of the bound P(L = 1)-states in these ions and other three-body systems. Highly accurate results (total energies) for the singlet and triplet P(L = 1)-states in the He atom(s) can be found in [16].

As follows from the results of our highly accurate computations of the singlet and triplet 2P(L = 1)-states in a number of two-electron ions we obtain a level of accuracy with the approach developed here that is very close to the accuracy of an earlier method from [8] which was specifically oriented to calculate the bound states in three-body systems with small angular momenta L. Computational times for both methods are also comparable to each other. This indicates a very high efficiency of our current approach for bound states with small L. Plus, now we have analytical formulas for bound three-body states with arbitrary L. Our computational interest in the bound P(L = 1)-states is based on the following facts. First, only for the bound P(L = 1)states can one find results determined to very high numerical accuracy, comparable to the accuracy known for the ground and low-lying excited S(L = 0)-states. Second, the problem of optimization of the non-linear parameters in Eq. (18) can be solved in a very fast and accurate way for all bound states with L = 1. Formally, for bound *P*-states there is no difference in our optimization algorithms from the case of the ground state(s) in three-body systems. For rotationally exicted states with L > 2 the process of optimization of the non-linear parameters is significantly more complicated and takes substantial computational times. For instance, for the bound 3D-states in the He atom our current method produces the following total energies: -2.0556207328528(4) a.u. (singlet) and -2.0556363094537(4) a.u. Note that such an accuracy for these states is not very high (it is comparable to the accuracy known for these states at the end of 1990s). To obtain better overall accuracy one needs to use a better optimization technique for the non-linear parameters in the trial wave functions. On the other hand, all highly accurate calculations of the bound states with $L \ge 2$ can be performed with the use of the quadruple precision only. Even in calculations of the bound D-states with N = 3,500-4,000 (N is the total number of basis functions) there is no need to use the extended arithmetical precision [17], since the corresponding overlap matrixes are not ill-conditioned. On the other hand, the total energies and other bound state properties of such states are determined (with these wave functions) to the accuracy 14–15 decimal digits. Briefly, we can say that the new optimization and computational strategies must be developed for the rotationally excited bound states with $L \ge 2$ to produce results which contain 20–25 stable decimal digits. Right now, we do not have such strategies and this is the main reason why we have restricted this study to the bound *P*-states only.

Note that the matrix elements of the potential energy are written in the form of Eq. (14) only in those cases when all interparticle interaction potentials are scalar functions of interparticle distances r_{32} , r_{31} and r_{21} . Such cases include Coulomb three-body systems and three-body systems in which the potential energy is written in the form $V_a(r_{32}) + V_b(r_{31}) + V_c(r_{21})$. In more complex cases the interaction potential between each pair of particles can also be a function of angular coordinates. In the general case, such potentials can be approximated by the sums of bipolar harmonics with the different *L* and *M* values. Analytical formulas for the matrix elements in such cases must include angular integrals of the products of three bipolar harmonics.

Let us discuss the formulas for the products of three bipolar harmonics $\mathcal{Y}_{L_aM_a}^{\ell_1\ell_2}(\mathbf{r}_{31},\mathbf{r}_{32})$, $\mathcal{Y}_{L_bM_b}^{\ell_3\ell_4}(\mathbf{r}_{31},\mathbf{r}_{32})$ and $\mathcal{Y}_{L_cM_c}^{\ell_5\ell_6}(\mathbf{r}_{31},\mathbf{r}_{32})$. The general formulas for such products can be found in [1]. It is clear that the angular integral of the product of three bipolar harmonics must be proportional to the Clebsh–Gordan coefficient $C_{L_bM_bL_cM_c}^{L_aM_a}$, or to the corresponding 3jm-symbol (see below). Second, as we have mentioned above, the (2L + 1) bipolar harmonics $\mathcal{Y}_{LM}^{\ell_1\ell_2}(\mathbf{r}_{31},\mathbf{r}_{32})$ (with the same L, but different M) are the basis vectors of the (2L + 1)-dimensional representation of the rotation group. Therefore, as it follows from Schur's lemma the angular integral of the product of two bipolar harmonics $\mathcal{Y}_{L_aM_a}^{\ell_1\ell_2}$ is always zero unless the values of L_a , M_a and

 L_b , M_b are exactly the same, i.e. $L_a = L_b$ and $M_a = M_b$. This explains the explicit form of the angular integral used in Eq. (6). For the product of three bipolar harmonics the situation is different and we cannot assume a priori that even some of the indexes are equal. In general, the angular integral of the product of three bipolar harmonics is written in the form

$$\oint d\Omega \mathcal{Y}_{L_a M_a}^{\ell_1 \ell_2} (\mathbf{r}_{31}, \mathbf{r}_{32}) \mathcal{Y}_{L_b M_b}^{\ell_3 \ell_4} (\mathbf{r}_{31}, \mathbf{r}_{32}) \mathcal{Y}_{L_c M_c}^{\ell_5 \ell_6} (\mathbf{r}_{31}, \mathbf{r}_{32})
= \begin{pmatrix} L_a \ L_b \ L_c \\ M_a \ M_b \ M_c \end{pmatrix} \times G_{\ell_2, \ell_4, \ell_6; \ell_1, \ell_3, \ell_5}^{L_a L_b L_c} (r_{32}, r_{31}, r_{21})
= \begin{pmatrix} L_a \ L_b \ L_c \\ M_a \ M_b \ M_c \end{pmatrix} \sum_{\lambda} b_{\lambda} r_{32}^{\ell_2 + \ell_4 + \ell_6} r_{31}^{\ell_1 + \ell_3 + \ell_3} P_{\lambda}(x)$$
(19)

where the function $G_{\ell_2,\ell_4,\ell_6;\ell_1,\ell_3,\ell_5}^{L_aL_bL_c}(r_{32},r_{31},r_{21})$ depends upon three relative coordinates r_{32}, r_{31} and r_{21} . The explicit formula for this function is obtained from the last equality in Eq. (19). The coefficient b_{λ} in Eq. (19) does not depend upon the relative coordinates, but it is a functions of all ten values of angular momenta $\lambda, L_a, L_b, L_c, \ell_1, \ell_2, \ell_3, \ell_4, \ell_5, \ell_6$. The formula for these coefficients takes the form

$$b_{\lambda} = \frac{1}{8\pi} (-1)^{L_{b}+\lambda} \sqrt{[L_{a}][L_{b}][L_{c}][\ell_{1}][\ell_{2}][\ell_{3}][\ell_{4}][\ell_{5}][\ell_{6}]} \cdot [\lambda] \\ \times \sum_{\lambda_{1}} \sum_{\lambda_{2}} \begin{pmatrix} \ell_{1} \ \ell_{5} \ \lambda_{1} \\ 0 \ 0 \ 0 \end{pmatrix} \begin{pmatrix} \ell_{2} \ \ell_{6} \ \lambda_{2} \\ 0 \ 0 \ 0 \end{pmatrix} \\ \times \begin{pmatrix} \lambda \ \ell_{3} \ \lambda_{1} \\ 0 \ 0 \ 0 \end{pmatrix} \begin{pmatrix} \lambda \ \ell_{4} \ \lambda_{2} \\ 0 \ 0 \ 0 \end{pmatrix} \begin{bmatrix} \ell_{3} \ \ell_{4} \ L_{b} \\ \lambda_{2} \ \lambda_{1} \ \lambda \end{bmatrix} \begin{bmatrix} \ell_{3} \ \ell_{4} \ L_{a} \\ \ell_{5} \ \ell_{6} \ L_{c} \\ \lambda_{1} \ \lambda_{2} \ L_{b} \end{bmatrix}.$$
(20)

In this form Eqs. (19, 20) look very similar to Eq. (6). Numerical calculations of the b_{λ} coefficients with the use of Eq. (20) is straightforward. For instance, for $\ell_1 = 1$, $\ell_2 = 3$, $\ell_3 = 2$, $\ell_4 = 2$, $\ell_5 = 2$, $\ell_6 = 2$ and for $L_a = 1$, $L_b = 2$, $L_c = 1$ one finds from Eq. (20) $b_1 = 0.15921224404155089 \cdot 10^{-1}$, $b_3 = -0.67600638318413508 \cdot 10^{-2}$ and $b_5 = 0.27451117819426586 \cdot 10^{-2}$. The coefficients b_{λ} with other values of λ equal zero identically.

Finally, as it seen from the formulas, Eqs. (19, 20) and Eq. (11), the calculation of the three-body integralas which contain the products of three bipolar harmonics is reduced to the computation of some finite sums of the basic (or auxiliary) three-body integrals $\Gamma_{k;l;n}(\alpha, \beta, \gamma)$, Eq. (14). The explicit expression for the radial integral of the $\int_{\ell_2,\ell_4,\ell_6;\ell_1,\ell_3,\ell_5}^{L_aL_bL_c} (r_{32}, r_{31}, r_{21})$ function is

$$T^{L_{a}L_{b}L_{c}}_{\ell_{2},\ell_{4},\ell_{6};\ell_{1},\ell_{3},\ell_{5}} = \int \int \int G^{L_{a}L_{b}L_{c}}_{\ell_{2}+\ell_{4}+\ell_{6};\ell_{1}+\ell_{3}+\ell_{5}}(r_{32},r_{31},r_{21})r_{32}r_{31}r_{21}dr_{32}dr_{31}dr_{21}$$
$$= \sum_{\lambda} b_{\lambda}I_{\ell_{2}+\ell_{4}+\ell_{6};\ell_{1}+\ell_{3}+\ell_{5}}(\alpha,\beta,\gamma;P_{\lambda}),$$
(21)

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where $I_{\ell_2+\ell_4+\ell_6;\ell_1+\ell_3+\ell_5}(\alpha,\beta,\gamma;P_{\lambda})$ is defined by Eq. (16). This is another result which is of great interest for highly accurate computations of many actual threebody systems. Our test calcualtions of the $T_{\ell_2,\ell_4,\ell_6;\ell_1,\ell_3,\ell_5}^{L_aL_bL_c}$ coefficient performed for $\ell_1 = 1, \ell_2 = 3, \ell_3 = 2, \ell_4 = 2, \ell_5 = 2, \ell_6 = 2, L_a = 1, L_b = 2, L_c = 1$ lead to the following result: $T_{3,2,2;1,2,2}^{121} = 1.9488412125971230 \cdot 10^4$.

We have considered the products of the two and three bipolar harmonics $\mathcal{Y}_{LM}^{\ell_1\ell_2}(\mathbf{r}_{31},\mathbf{r}_{32})$. It is shown that angular integrals of such products are represented as the finite sums of powers of the three relative coordinates r_{32} , r_{31} and r_{21} (or interparticle distances). The six-dimensional (angular + radial) integrals of the products of the two and three bipolar harmonics in the basis of exponential radial functions are expressed as finite sums of the auxiliary three-particle integrals $\Gamma_{n,k,l}(\alpha, \beta, \gamma)$. The formulas derived in this study can be used to accelerate highly accurate computations of rotationally excited (bound) states in arbitrary three-body systems. The methods developed in this study have been used to construct very compact (but highly accurate!) variational wave functions of triplet and singlet 2P(L = 1)-states in light two-electron atoms and ions. The preliminary results of our highly accurate calculations of the triplet and singlet 2P(L = 1)-states in the two-electron Li⁺, Be²⁺, B³⁺ and C⁴⁺ ions contain 20–21 stable decimal digits. This makes our wave functions among the most accurate wave functions ever known for these atomic systems.

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